

Data-driven Warping of Gaussian Processes for Spatial Interpolation of Skewed Data

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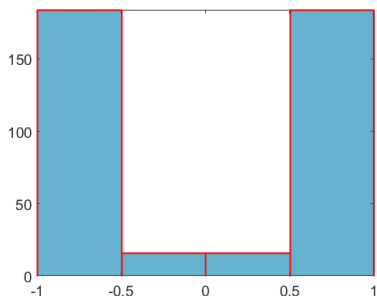
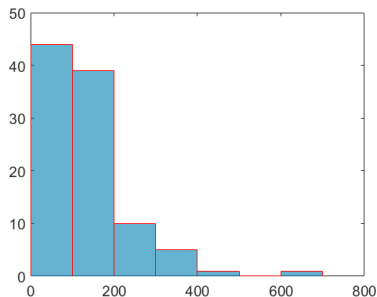
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Motivation

- Generating **accurate estimates and maps** from sparse, non-Gaussian data remains a challenge.
- Observed data distributions do not always comply with **explicit mathematical models**.
- **Machine learning** is in fashion; how does geostatistics fit in?



What are Gaussian Process Regression (GPR) and Data-driven Warping?

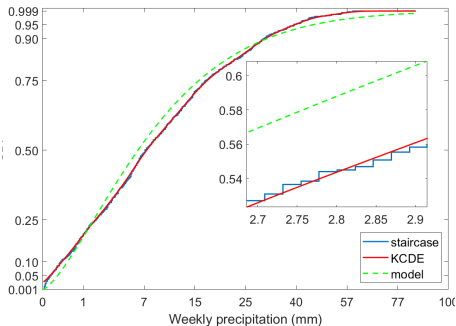
- Gaussian processes are Gaussian random fields defined in feature spaces.
- GPR prediction is “equivalent” to kriging in feature space.
- “Warping” the process means applying a nonlinear transform to normalize the data before the regression step [Snelson et al., 2004].
- Data-driven warping means that the warping transform is learned from the data using a non-parametric, kernel-based estimator.

(1) Agou, Pavlides, Hristopulos. “Spatial Modeling of Precipitation Based on Data-Driven Warping of Gaussian Processes.” *Entropy* 2022, 24, 321.

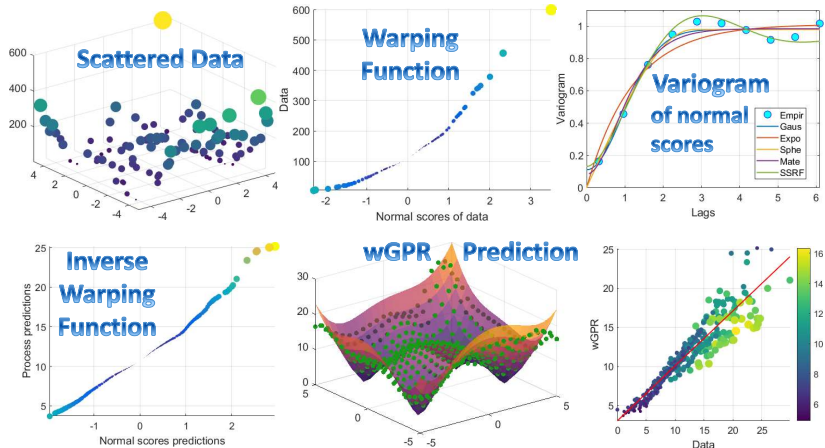
(2) Pavlides, Agou, Hristopulos. “Non-parametric Kernel-Based Estimation of Probability Distributions for Precipitation Modeling.” *arXiv preprint*, arXiv:2109.09961 (2021).

Learning the Cumulative Distribution Function using Kernels

- Kernel functions are used to estimate the CDF.
- CDF steps are smoother than the staircase estimate.
- A theoretical model of the probability distribution is not necessary.



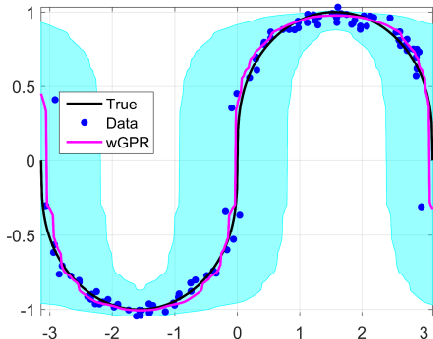
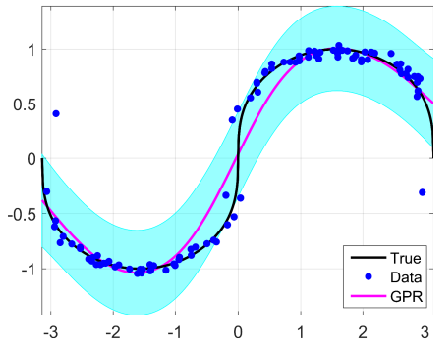
Warped Gaussian Process Regression in a Nutshell



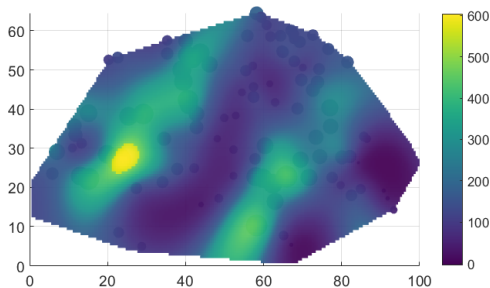
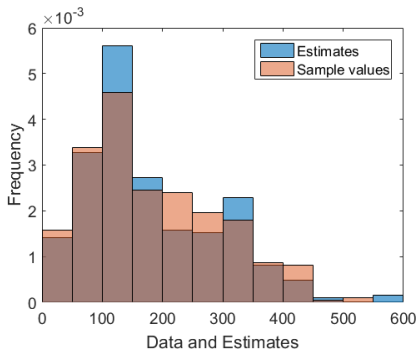
Gaussian Process Regression (GPR) compared to wGPR for Test Function

$$x(\mathbf{s}) = [\sin(\pi\mathbf{s}) + \sigma_\epsilon \epsilon(\mathbf{s})]^{1/3}, \quad \mathbf{s} \in [-1, 1]$$

$$\sigma_\epsilon = 0.1, \quad \epsilon(\mathbf{s}) \sim \mathcal{N}(0, 1)$$



Example: SIC 1997 Swiss Rainfall Data

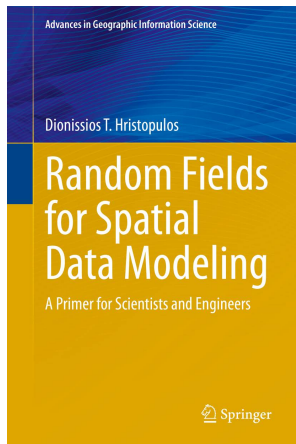


Training: 100 points. **Validation:** 367 points. **Map Grid:** 6251 point inside convex hull. **Optimal variogram:** Spartan variogram (Boltzmann-Gibbs with gradient and curvature terms). **Kernel for warping:** Epanechnikov.

Contributions

- We introduce **data-driven warping** which is a flexible, non-parametric approach for normalizing non-Gaussian data.
- Our approach differs from others because the normalizing transform is expressed in terms of **kernel functions and the data values**.
- In **data-driven wGPR** we combined **data-driven warping** with Gaussian process regression, leading to a more flexible spatial prediction method than **GPR**.
- wGPR allows us to use commonly known geostatistical methods in the broader framework of **Gaussian processes**.

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